IN THE CLAIMS:

Please amend the claims as follows:

Sub B1

1. ~~(Amended) A piste maintenance tracklaying vehicle~~ [(1)] comprising an internal combustion engine [(2)] which is drivingly connected, preferably via a gear [(3, 13, 14)], to a drive sprocket [(4)] of each track [(5)], and accessory drives [(6)] for additional devices [(7, 8, 9)] that are mountable on said tracklaying vehicle [(1)], such as rotary snow plow, front snow [plow] blower, or the like, and/or for vehicle components [(15, 16, 17)], such as a tilting device for [a] platform and driver's cab or track tensioner, [characterized in that said] with an internal combustion engine [(2) is] being connected via a generator [(10)] and at least one electric motor [(11, 12)] and possibly a gear [(13, 14)] to each drive sprocket [(4)], and in overrun mode said electric motor [(11, 12) is] being switchable as a current generator for accessory drives [(6)] designed as electrohydraulic or electric drives [(18, 19)], wherein at least said electric drive [(19)] for a shaft of said rotary snow plow [being] is synchronized with the electric motor [(11, 12)] of ~~said drive sprocket~~ [(4)].

2. (Amended) The tracklaying vehicle according to claim 1, [characterized in that] wherein each drive sprocket [(4)] is drivingly connected to a separate electric motor [(11, 12)].

Sub B2

~~3. (Amended) The tracklaying vehicle according to claim 1, [or 2, characterized in that]~~ wherein a ~~planetary gear [(13, 14)] is arranged between electric motor [(11, 12)] and drive~~

~~sprocket [(4)], and a steering gear [(3)] is arranged in the case of only one electric motor [(11, 12)] for the drive sprocket [(4)] of both tracks [(5)].~~

4. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein a hydraulic medium for said electrohydraulic drive [(18)] is a medium based on water.

5. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said tracklaying vehicle [(1)] is designed with an energy buffer [(20)] which ~~can~~ may be fed by said generator [(10)] or by said electric motor [(11, 12)] which operates as a generator.

6. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said tracklaying vehicle [(1)] further comprises an electronic high-performance means [(21)] for controlling travel engines or motors [(2, 11, 12)] and/or accessory drives [(6)].

7. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said internal combustion engine [(2)] comprises an electronic engine control.

8. (Amended) ~~The~~ tracklaying vehicle according to [at least one of the preceding claims, characterized in that at least the] claim 1, wherein electrohydraulic function units [(22, 23)] for performing vehicle functions [(15.18a)], for instance of the front and rear device carrier, are arranged in a decentralized manner and comprise an electric motor, a pump, a control block and a hydraulic medium tank.

9. (Amended) The tracklaying vehicle according to [any one of the preceding claims, characterized in that] claim 6, wherein said electronic high-performance means [(21)] is centrally arranged in said tracklaying vehicle [(1)] for distributing energy to all consumers [(6 to 9, 11, 12, 15 to 24)] and for energy feedback.

10. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein all components [(2, 3, 6 to 12, 15 to 25)] of said tracklaying vehicle are composed in the manner of modules.

11. (Amended) ~~The tracklaying vehicle according to~~ [at least one ~~of the preceding~~ claims, ~~characterized in that~~] claim 3, wherein ~~said~~ tracklaying vehicle [(1)] comprises a parking brake, in particular ~~as a multidisc~~ brake integrated in the planetary gear [(13, 14)] which is operable by ~~a hydraulic medium~~ based on water.

12. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said tracklaying vehicle [(1)] comprises a winch [(24)] with an electric drive [(19)].

13. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said tracklaying vehicle [(1)] comprises a winch [(24)] with an electric drive [(19)] designed for feeding back energy during downhill driving.

14. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said tracklaying vehicle [(1)] comprises an energy feeding means for the supply of external energy.

15. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 14, wherein said energy feeding means is designed as a trailing cable or as a coupling system which is adapted to be coupled with contact wired or current rails.

16. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein said tracklaying vehicle [(1)] has an interconnection means for the energetic connection to at least one further tracklaying vehicle.

17. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 6, wherein a heating means of said tracklaying vehicle [(1)] is fed with waste feed from the motors [(11, 12)] of the hydraulic system [(18)] and/or said electronic high-performance means [(21)].

18. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 6, wherein said tracklaying vehicle [(1)] comprises at least one setpoint transmitter for at least the desired traveling speed.

19. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 18, wherein said electronic high-performance means [(21)] or [said]

a vehicle control unit, respectively, is connected to said setpoint transmitter and comprises an electronic evaluation means at least for determining consumption-optimum speeds for said internal combustion engine [(2)].

20. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein the gear ratio of snow plow shaft to drive sprocket is adjustable.

21. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 1, wherein a diagnosis means is arranged on said tracklaying vehicle [(1)] for maintenance and inspection of [the] an electric control unit [(21, 22, 23)].

22. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 18, wherein said setpoint transmitter is designed as an accelerator for controlling speed and for braking purposes.

23. (Amended) The tracklaying vehicle according to [at least one of the preceding claims, characterized in that] claim 18, wherein [the] a predetermined setpoint is a setpoint of the electric motor speed.